

Math 132: Differential Topology

§ Transversality

Def We say two smooth submanifolds $M, M' \subset N$ are transversal at $p \in M \cap M'$ if $T_p M + T_p M' = T_p N$.
If they are transversal at every point $p \in M \cap M'$, we simply say they are transversal, and write $M \pitchfork M'$.

Def More generally, we say a smooth map $f: M \rightarrow N$ is transversal to a submanifold $M' \subset N$ (abbreviated $f \pitchfork M'$) if $\text{Image}(df_p) + T_q M' = T_q N$ for every $p \in f^{-1}(M')$.

$\swarrow \quad \searrow$
 $q = f(p)$

Examples



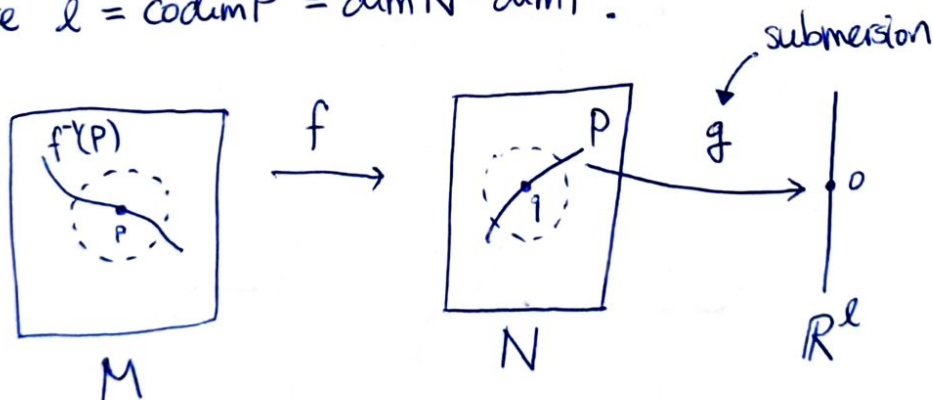
2/

The following theorem generalizes the preimage theorem for regular values:

Thm If $f: M \rightarrow N$ is a smooth map transversal to a submanifold $P \subset N$, then the preimage $f^{-1}(P) \subset M$ is a submanifold of M , whose codimension (i.e. $\dim M - \dim f^{-1}(P)$) equals that of $P \subset N$ (i.e. $\dim N - \dim P$).

proof) We need to show that every point $p \in f^{-1}(P)$ has a neighborhood U in M such that $f^{-1}(P) \cap U$ is a manifold.

Let $q = f(p)$. In a neighborhood of q , we may write P as the zero set of a collection of independent functions g_1, \dots, g_ℓ , where $\ell = \text{codim } P = \dim N - \dim P$.



Then, near p , $f^{-1}(P)$ is the zero set of $(g_1 \circ f, \dots, g_\ell \circ f) = g \circ f$, so it's enough to show that 0 is a regular value of $g \circ f$.

3/

Since $d(g \circ f)_p = dg_q \circ df_p$ and $dg_q: T_q N \rightarrow \mathbb{R}^l$ is surjective with $\ker dg_q = T_q P \subset T_q N$, 0 is a regular value of $g \circ f$ if and only if $\text{Image}(df_p) + T_q P = T_q N$, which is exactly our transversality assumption. ■

Cor If $M, M' \subset N$ are two transversal submanifolds, then $M \cap M'$ is also a submanifold, with $\text{codim}(M \cap M') = \text{codim } M + \text{codim } M'$.

Rmk Additivity of codimension is very natural.

Think: cutting out a submanifold locally using $k = \text{codim } M$ and $l = \text{codim } M'$ independent functions.

§ Homotopy and stability

Def We say two smooth maps $f_0, f_1: M \rightarrow N$ are homotopic, abbreviated $f_0 \sim f_1$, if there exists a smooth map $F: M \times I \rightarrow N$ such that $F(x, 0) = f_0(x)$ and $F(x, 1) = f_1(x)$. We call such F a homotopy between f_0 and f_1 .

↖ $f_t(x) = F(x, t)$
is a smoothly evolving
family of maps

4/

Homotopy is an equivalence relation on smooth maps from M to N , and the equivalence class to which a map belongs is called its homotopy class.

Def A property of smooth maps is called stable if whenever $f_0: M \rightarrow N$ possesses the property and $f_t: M \rightarrow N$ is a homotopy of f_0 , then, for some $\varepsilon > 0$, each f_t with $t < \varepsilon$ also possesses the property.

Thm (Stability theorem)

The following classes of smooth maps of a compact manifold M into a manifold N are stable classes:

- local diffeomorphisms
- immersions
- submersions
- maps transversal to a given ^{closed} submanifold $P \subset N$
- embeddings
- diffeomorphisms

(See [Guillemin-Pollack] pp. 36-37 for the proofs.)